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Unsteady Galloping of Bridge Decks during the Launching Phase



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UNSTEADY GALLOPING OF BRIDGE DECKS DURING THE LAUNCHING PHASE

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by

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^{*)} Either the German or the Italian form of the title may be used.

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To my dear grandpa, Guangzhi Chen

“carving words into stone”

Death’s End (The Three-Body Problem III), by Cixin Liu

Preface

This doctoral thesis was written during the last period of my stay at the Institute of Steel Structures, TU-Braunschweig. I was financially supported by the China Scholarship Council to carry out a doctoral study in Germany. My research began with the fatigue problem of steel structures, but wind engineering gradually attracts me more and I finally decided to work in this area.

Prof. Klaus Thiele, my supervisor, deserves my first and most gratitude, continuously supporting me and this research from every aspect. Moreover, under his supervision, I was given the most freedom to pursue my research interests. I also want to thank Prof. Mathias Clobes, for introducing this research topic to me and continuously encouraging me to carry on with it.

I am very lucky that I have joined the international Ph.D. program between TU-Braunschweig and the University of Florence. With this bridge, I am able to collaborate with the famous wind engineering group at the University of Florence. I am very grateful to Prof. Gianni Bartoli being my Italian tutor, and special thanks must be given to Prof. Claudio Mannini for the many deep and inspiring discussions between us. Thanks to Bernardo Nicese, Dr. Giacomo Zini, Dr. Andrea Giachetti, Dr. Tommaso Massai, Dr. Antonino Maria Marra, Niccolò Barni, and all the other Italian colleagues, I have enjoyed my exchange stay in Florence with their accompany.

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Abstract

The present work deals with the unsteady galloping instability, which arises at low reduced flow velocities, for steel-concrete composite bridge decks during the incremental launching phase. In this particular situation, the light weight and bluff shape of the steel box, which is normally first launched, imply a high proneness to the risk of unsteady galloping. The main goal of this thesis is to understand the unsteady galloping with respect to these special cross sections, which have not been investigated in depth before, and to develop an analytical approach for the modeling of unsteady galloping as a basis for design of bridges.

Wind tunnel tests on three sectional models, among which are a generic bridge deck model with typical open cross section and two reference cylinder models, confirmed the high proneness to unsteady galloping instability for the particular situation of bridge launching. Especially, the typical unsteady galloping which arises due to the interaction with Kármán-vortex induced vibration was observed at the 4° mean flow incidence of the bridge deck model, fixing the galloping onset at the Kármán-vortex resonance wind speed up to a quite high Scruton number (the mass-damping parameter). Moreover, the sensitivity of unsteady galloping behaviors to mean flow incidence was highlighted. At the null mean flow incidence of the bridge deck model, the unsteady galloping was initiated in less understandable manner, being the onset velocity clearly higher than the Kármán-vortex resonance one even for a very low Scruton number.

Subsequently, mathematically modeling the unsteady galloping was carried out, with a modified form of Taumra's nonlinear wake oscillator model. Satisfying predictions have been achieved not only for a 2:1 rectangular cylinder, but also for the bridge deck model at its 4° mean flow incidence. In particular, the typical unsteady galloping behavior, that lower than a certain value of Scruton number galloping arises at the Kármán-vortex resonance wind speed, is well captured by the wake oscillator model. Attention was also paid to the so-called physical considerations in the wake oscillator model. Further modifications for the wake oscillator model were consequentially proposed, exhibiting better agreements with the physics of the near-wake of sharp-edged bluff body, maintaining at the same time a good capability for the predictions of unsteady galloping behaviors.

Finally, the wake oscillator model was further extended for continuous structural system, based on coupling multiple wake oscillators to the structural system via finite element method.

A case study, concerning a steel-concrete composite bridge during the critical launching phase, was presented. In particular, by taking into account the aerodynamic contributions of a lattice launching nose, the potentiality of efficiently suppressing the galloping instability through aerodynamic optimization for the launching nose was revealed in the case study. This has promoted consequent wind tunnel tests on the further optimized launching nose, which combined with numerical predictions from the wake oscillator model further confirmed the aforementioned potentiality.

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Notations

Symbols for matrix and vector are extra indicated with bold font

Greek Variables

α	wind angle of attack or torsional degree of freedom
α_0	mean wind angle of attack (for oscillation body)
β, λ	coefficients in Tamura's nonlinear wake oscillator model
ϕ_i	mode shape vector for structure
Φ, Φ_e	mode shape matrix for structure, and the expanded one
ψ_s, ψ_{sr}	displacement vector for a structural system, and its reduced form due to boundary conditions
ψ_t, ψ_{tr}	displacement vector for combined system of structure and wake oscillators, and its reduced form due to boundary conditions
ψ_{tn}	the normalized forms of ψ_{tr} , by expanded mode shape matrix Φ_e
ϑ, ϑ_r	displacement vector for wake oscillators, and its reduced form due to boundary conditions
ξ	vector collected the generalized displacement in mode space
δ_0	logarithmic mechanical damping
δ_s	shear layer thickness
ϵ	fraction of vorticity in shear layer being transferred to downstream mature vortex
γ	mode shape factor in VIV theories
μ	dynamic viscosity of flow
ω	circular frequency
ω_0	circular natural frequency
ϕ	mode shape function
$\Phi(\tilde{\tau})$	<i>Wagner's function</i>

ρ	air density
ρ_r	correlation coefficient between two points of a distance of r
$\rho_{u,u}$	normalized auto-correlation function of $u(t)$
σ_L	standard deviation of fluctuation lift due to vortex shedding
σ_u	standard deviation of fluctuation part of longitudinal wind speed
τ	reduced time, defined through body's natural circular frequency $\tau = \omega_0 t$
τ_{lag}	reduced time lag
$\tilde{\mu}$	tiny number
$\tilde{\tau}$	reduced time defined as Ut/b_h
v	ratio of V to V_r
v_s	ratio of U_s to U
Γ	circulation of a vortex
φ	phase angle
φ_{lag}	phase lag
φ_{Lm}	phase angle by which motion-induced lift leads body's displacement, defined in a range $-\pi \leq \varphi_{Lm} \leq \pi$
ϑ	near-wake inclination angle in Tamura's nonlinear wake oscillator model
ϑ_{eff}	effective rotation angle of near-wake lamina for generating vortex shedding force on oscillation body
ξ_i	the generalized displacement in mode space (corresponding to its mode shape vector ϕ_i)
ζ_0	mechanical critical damping ratio

Latin variables and Constants

\tilde{U}, \tilde{V}	instantaneous longitudinal and lateral wind speed
$\bar{c}_i, \tilde{c}_i, \bar{k}_i$	diagonal elements for \bar{C} , \tilde{C} and \bar{K} matrices
\bar{r}	$r = \frac{\bar{Y}_s}{\bar{V}}$
\bar{Y}	non-dimensional amplitude of Y
\bar{Y}_s	steady-state non-dimensional amplitude
$\bar{I}_r, \bar{C}_r, \tilde{C}_r, \bar{K}_r$	the reduced forms of \bar{I} , \bar{C} , \tilde{C} and \bar{K} , after applying boundary conditions
$\bar{I}, \bar{C}, \tilde{C}, \bar{K}$.	mass of inertia, linear damping, nonlinear damping and stiffness matrices for multiple wake oscillators

- $\hat{A}_r, \hat{B}_r, \hat{G}_r, \hat{H}_r$ the reduced forms of $\hat{A}, \hat{B}, \hat{G}$ and \hat{H} , after applying boundary conditions
- $\hat{A}, \hat{B}, \hat{G}, \hat{H}$. matrices responsible for the coupling between structure and wake oscillators
- M_s, C_s, K_s mass, damping and stiffness matrices for a structural system
- $M_t, C1_t, C3_t, K_t$ global mass, linear-damping, nonlinear-damping and stiffness matrices, for combined degrees of freedom of structure and wake oscillators
- M_{sr}, C_{sr}, K_{sr} the reduced forms of M_s, C_s and K_s , after applying boundary conditions
- $M_{tn}, C1_{tn}, C3_{tn}, K_{tn}$ the normalized forms of $M_{tr}, C1_{tr}, C3_{tr}$ and K_{tr} , by expanded mode shape matrix Φ_e
- $M_{tr}, C1_{tr}, C3_{tr}, K_{tr}$ the reduced forms of $M_t, C1_t, C3_t$ and K_t , after applying boundary conditions
- q_s external force vector for a structural system
- q_t, q_{tr} external force vector for combined system of structure and wake oscillators, and its reduced form due to boundary conditions
- q_{QS}, q_{Qsr} quasi-steady transverse force vector, and its reduced form due to boundary conditions
- q_{tn} the normalized forms of q_{tr} , by expanded mode shape matrix Φ_e
- $\hat{a}_i, \hat{b}_i, \hat{g}_i, \hat{h}_i$.. elements for $\hat{A}, \hat{B}, \hat{G}$ and \hat{H} matrices
- \hat{e}_i coefficient for elements in q_{QS} vector
- $\bar{I}_u, \bar{I}_v, \bar{I}_w$ averaged I_u, I_v and I_w , of spatially discrete points
- \bar{L}_u averaged L_u of spatially discrete points
- \bar{U} averaged U of spatially discrete points
- $\tilde{a}, \tilde{b}, \tilde{c}$ parameters in Corless&Parkinson's model
- \tilde{w} downwash
- a combined with b_h to indicate of the position of elastic center, for elastically supported body
- A_1 galloping factor according to quasi-steady theory
- A_i coefficients of polynomials approximating $C_{Fy}-\alpha$ curve (galloping factor A_1 corresponds to the linear slope)
- $A_{1, equ}$ equivalent galloping factor for a continuous system
- b width of wind tunnel model or bridge deck (chord length)
- b_h half chord length
- b_{avg} averaged value of top and bottom widths of a wind tunnel model

$C(k), F(k), G(k)$	<i>Theodorsen's circulation function</i> , as well as its real and imaginary part
c_α	damping for torsional degree of freedom
C_D, C_L, C_M ..	drag, lift and moment coefficient (steady part)
c_g	width of the strip of turbulence grid
C'_L, c'_L	standard deviation of lift coefficient fluctuation for the entire prism body and for a unit length of the prism body
C_v	unsteady lift coefficient due to vortex exciting in Corless&Parkinson's model
c_y	damping for heaving degree of freedom
c_\varnothing	coefficient related to the damping force for oscillation near-wake lamina, according to unsteady thin airfoil theory
C_{Fy}, C_{Fy}^{QS}	transverse force coefficient according to quasi-steady theory
$C_{L,un}$	unsteady lift due to effective rotation angle of near-wake lamina, in Tamura's nonlinear wake oscillator model
C_{L0}, c_{L0}	sinusoidal equivalent amplitude of the fluctuation lift coefficient due to vortex shedding for the entire prism body, and for a unit length of the prism body
$C_{lat,0}$	RMS value of the fluctuation lift coefficient due to vortex shedding
C_{Lm0}	amplitude of motion-induced lift coefficient
C_{LmR}, C_{LmI} ..	portion of C_{Lm0} in phase with $y(t)$, and in phase with $\dot{y}(t)$
C_{Lm}	motion-induced lift coefficient
C_{m0}	potential flow inertia coefficient in Luo&Bearman's model
C_{pb}	base pressure coefficient of bluff body
C_R	derived coefficient for F_R
d	height of wind tunnel model or bridge deck
D, L, M	aerodynamic drag, lift and moment (steady part)
d_g	mesh size of turbulence grid
d_{ref}, l_{ref}	reference height and length for launching nose model
E	Young's modulus
e	combined with b_h to indicate of the position of gravity center, for elastically supported body
f	slope of the unsteady vortex-excited lift coefficient to the near-wake inclination \varnothing in Tamura's nonlinear wake oscillator model
F_b	force reaction due to boundary support

F_L	restoring force of near-wake lamina
F_R	lift variation on near-wake lamina, due to its circulation change induced by vortex discharging
F_y	transverse aerodynamic force
G	gravity center of near-wake lamina
h	width of near-wake behind bluff-body
h^*	non-dimensional form of h , defined h/d
H_i^*, A_i^*	flutter derivatives
$H_n(k)$	Hänkel's functions
h_{avg}	$(h_{std}+h_{sk})/2$
h_{sk}	wake width determined by the distance between minus peaks of skewness of \tilde{U} , being \tilde{U} transversely measured in the near-wake of bluff body
h_{std}	wake width determined by peak distance of $\text{std}(\tilde{U})/U_0$, being \tilde{U} transversely measured in the near-wake of bluff body
I	mass moment of inertia at elastic center
i	$i = \sqrt{-1}$, or used as number counter
I_\varnothing	mass moment of inertia for near-wake lamina
I_u, I_v, I_w	turbulence intensities
$I_{\varnothing,a}$	the added inertia of moment for oscillation near-wake lamina, according to unsteady thin airfoil theory
I_{xx}	second moment of area of a cross section
$J_n(k), Y_n(k)$..	modified Bessel's functions of first and second kind
K	reduced frequency defined as $b\omega/U$
k	reduced frequency defined as $b_h\omega/U$
k_α	stiffness for torsional degree of freedom
k_\varnothing	equivalent rotational stiffness for near-wake lamina
k_y	stiffness for heaving degree of freedom
l	half length of near-wake behind bluff-body
l^*	non-dimensional form of l , defined l/d
l_e	effective length of sectional wind tunnel model (between two end-plates)
l_F	vortex formation length
L_u	longitudinal turbulence integral length

l_V, h_V	streamwise distance and across-flow distance of vortex pairs
$l_{F,net}$	net near-wake length, starting from rear-face of body to the end of near-wake
$l_{FL,O}$	distance between pivot point O and F_L being applied on near-wake lamina
l_{FL}	length scale for calulating the restoring force F_L on near-wake lamina
l_I	length scale for calulating I_ϑ of near-wake lamina
$l_{s,i}$	spanwise reference length for aerodynamic force calculation at node i of a continuous system)
L_{y1}, L_{y2}, L_{y3}	components of theoretical lift on thin airfoil
m	mass of body per unit length
m^*	mass ratio between body and air
M_ϑ	moment of an oscillation near-wake lamina, according to unsteady thin airfoil theory
M_e	effective oscillation mass of wind tunnel model
$M_{\alpha 2}$	component of theoretical moment on thin airfoil
m_{ij}, c_{ij}, k_{ij}	elements for M_s , C_s and K_s matrices
N	nodes of a structural system
n	frequeuncy in Hz
n_0	natural frequency in still air
n_m	frequency at which a wind tunnel model is forced to vibrate
n_o	oscillation frequency in flowing air
N_r, N_{sr}, N_{wr}	total amount of degrees of freedom for the combined system of structure and wake oscillators, as well as the portion respectively for structure and for wake oscillators
n_{st}	Strouhal frequency
n_{vs}	oscillation frequency of near-wake lamina
O	pivot point of near-wake lamina
p	rotational degree of freedom of beam
R	$R = \bar{Y}^2$
r	spanwise distance between two points on slender body
Re	Reynolds number
S_{LL}	power spectral density of fluctuating lift
S_{uu}	power spectral density of u

S_{yy}	power spectral density of y
Sc	Scruton number defined with d^2
Sc^*	Scruton number defined with bd
St	Strouhal number defined with d
t	physical time
T_u	integral time length
t_{lag}	physical time lag
U	mean wind speed
u, v, w	fluctuation part of longitudinal, lateral, and vertical wind speed
u', v', w'	standard deviation of u, v and w
U_g	critical wind speed for across wind galloping, according to quasi-steady theory
U_i	mean wind speed at a single point
U_r	critical wind speed for Kármán-vortex induced vibration
U_{rel}	resultant wind speed due to motion of body
U_S	mean wind speed at the flow separation point of bluff body
u_V	relative wind speed of vortex being transported downstream to incoming wind speed U
V	reduced wind velocity
V_0, V_1, V_2	characteristic reduced wind speeds for quasi-steady galloping response ($V_0 = V_g$)
V_g	reduced form of U_g
V_r	reduced form of U_r
V_{lb}	lower bound of V at which ϕ_{Lm} becomes always positive
x, y, z	Cartesian coordinate, or degrees of freedom
x_g	upstream distance of turbulence grid to axis of wind tunnel model
Y	non-dimensional displacement of body's motion, defined as y/d
$Y_1, \epsilon_{03}, \epsilon_{05}$...	coefficients in Gao&Zhu's model as a function of K
y_0	amplitude at which a wind tunnel model is forced to vibrate, or initial displacement for free-decaying motion
y_{rms}	RMS value of fluctuation part of $y(t)$

Other Symbols

\circ	Hadamard product
Δ	small increment or difference
$(\dot{}), ()'$	differentiation with respect to physical time t , and reduced time τ (or $\tilde{\tau}$)
∞	infinity
$\text{std}()$	standard deviation of a signal
$^{\top}$	transform operation for matrix or vector

Abbreviations

AEVS	Alternate Edge Vortex Shedding
CFD	Computational Fluid Dynamics
HFFB	High Frequency Force Balance
ILEV	Impinging Leading Edge Vortices
LEVS	Leading Edge Vortex Shedding
QS	Quasi Steady
RMS	Root Mean Square
TEVS	Trailing Edge Vortex Shedding
VIV	Vortex Induced Vibration